A NOVEL THRESHOLD BASED APPROACH OF DETECTING OIL SPILLS ON SEA IN SYNTHETIC APERTURE RADAR IMAGES

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<p>Received: 16/12/2020</p> <p>Revised: 16/01/2021</p> <p>Published: 04/02/2021</p> <p>KEYWORDS</p> <p>Oil spill detection</p> <p>SAR images</p> <p>Adaptive Thresholding</p> <p>Segmentation</p> <p>Classification</p>	<p>Nowadays, phenomena of oil spills commonly take place on rivers and sea, and cause severe consequences on the water environment. Therefore, detecting oil spills and providing early warnings of them have received great interests for recent decades. There have been many algorithms developed to identify oil spills using the Synthetic Aperture Radar images because of their quality independence of weather conditions and capability of event capture of a wide geometry range. Among them, the threshold based methods are quite popular in reality because of their implementation simplicity. However, these algorithms provide relatively low accuracy. The paper proposed a novel threshold based algorithm of oil spill detection in the Synthetic Aperture Radar images. This threshold is a global one determined according to statistical analysis of pixel intensities of the images and their sizes. The simulation results of the proposed method on Python software were compared with other methods, and proved that the proposed method significantly improved accuracy.</p>

MỘT CÁCH TIẾP CẬN MỚI DỰA TRÊN NGƯỠNG ĐỂ PHÁT HIỆN VẾT DẦU LOANG TRÊN BIỂN TRONG CÁC ẢNH RA ĐA MẶT MỞ TỔNG HỢP

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THÔNG TIN BÀI BÁO	TÓM TẮT
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1. Introduction

Oil spill detection on sea has been an attractive topic receiving great interests for recent decades because of practical demands and its challenges brought to image processing experts in particular and scientists in general. Annually, a huge amount of oil is poured into oceans due to oil leakages from ship collisions and accidents at manufactures producing petroleum on sea. More seriously, oil spills easily spread on wide areas because of strong winds and flows in ocean. Therefore, they could cause severe damages of the underwater environment if there is no solution to early warning and detecting them.

There is a variety of methods developed to identify, locate, and track oil spills on sea. However, there are two popular groups of methods of oil spill detection, namely optical image based [1] - [3], and Synthetic Aperture Radar (SAR) image based methods [4] - [6]. The latter methods are more advantageous than the former ones in terms of their coverage and relative independence of weather conditions. In fact, the detection of oil slicks using SAR image processing techniques is very popular in practice and specially applied in remote sensing systems of monitoring oil spills in wide areas.

Due to oil slicks occurring in SAR images as dark regions, a great challenge of oil spill detection is to separate dark areas corresponding oil slicks with other dark ones without deriving from real oil spills. In addition, reduction of impacts of speckle noises on the quality of SAR images is another challenge [7] - [9]. In order to detect oil spills, threshold based methods were early developed by Otsu in 1979 [10] - [12]. Although their accuracy is limited, they are still widely utilized in practice for its computational simplicity. The classical method for oil spill identification is Otsu's method [10], which is based a global single threshold value computed from the brightness distribution of an entire image to identify black areas corresponding to potential candidates of oil spills. However, the Otsu's algorithm only works well with gray level images with only bi-modal distribution in the gray level histogram, and fails when the histogram is not bi-modal but is uni-modal or multi-modal [11].

Another threshold based method is proposed by Bradley and Roth in 2007 [13] in which the threshold values were firstly locally computed at a neighbourhood of the pixel under consideration, then separating a pixel if it belongs to dark regions or not. Generally, adaptive thresholding solutions based on local thresholds; for example, using mean and Gaussian filters are also quite popular in image segmentation tasks because of their implementation simplicity [14].

This paper developed a novel algorithm of oil spill detection in SAR images, which is based on determining a global threshold to classify which pixels belong to dark regions or not. This algorithm can works well for both bi-modal and non-bimodal gray level images.

The remainder of the paper is organized as follows. Section 2 presents the methodology for the proposed method. In Section 3, we present some simulation results to evaluate the proposed algorithm performance in comparison with three other algorithms using Python software. In Section 4, we draw conclusions from the results of our evaluation and outline areas for future work.

2. Research methodology

Detection of dark spot is a first stage of the procedure of identifying oil spills in SAR images. The paper concentrates on detecting darks area in the SAR images. The block diagram of the system detecting dark spots in SAR images shown in Figure 1. In this paper, we focus on developing a new algorithm for the block of Adaptive Thresholding.

Figure 1. The block diagram of system detecting dark spots in SAR images

There are many adaptive thresholding methods for image segmentation such as adaptive mean thresholding (AMT), adaptive Gaussian thresholding (AGT), adaptive median thresholding, and adaptive thresholding using integral image. The first three thresholding methods standardized in the library of software Python 3.0 were used to compare with the proposed method.

In this paper, we proposed a new global thresholding method based on statistic probability theory. This global threshold is determined for every SAR image to identify oil spills. The proposed threshold is computed as a function of image sizes and pixel intensities. The global threshold assumed as α is calculated as follows.

$$\alpha = \frac{\alpha_1 + \alpha_2}{2} \quad (1)$$

$$\alpha_1 = \frac{\sum_{i=1:x} \sum_{j=1:y} I_{ij}}{xy} - \sqrt{\frac{\sum_{i=1:x} \sum_{j=1:y} \left(I_{ij} - \frac{\sum_{i=1:x} \sum_{j=1:y} I_{ij}}{xy} \right)^2}{xy}} \quad (2)$$

$$\alpha_2 = n - \sqrt{\frac{\sum_{i=1:x} \sum_{j=1:y} \left(I_{ij} - \frac{\sum_{i=1:x} \sum_{j=1:y} I_{ij}}{xy} \right)^2}{xy}} \quad (3)$$

where x is the number of pixels of an image row, and y is the number of pixels of an image column. I_{ij} is the pixel intensity at the position (i, j) . n is the pixel intensity which is the most repeated one in the image.

Based on the threshold computed by the equations (1), (2) and (3), pixels whose intensities lower than this threshold were assumed as dark points, else pixels as the white background. According to a oil feature in SAR images, the rightmost dark areas are potential candidates of high probability to be oil spills.

3. Simulation results and discussion

The simulations were performed on Python software with two stages. In the first stage, the simulations was implemented with the first original image shown in Figure 2(a) for four different methods which are adaptive mean thresholding (AMT), adaptive Gaussian thresholding (AGT), Otsu method, and the proposed method. In the second stage, the simulations was performed with the second original image shown in Figure 2(d) for these four methods. In addition, the first three methods were performed according to the standard library functions in Python software.

The SAR images selected to simulate the proposed algorithm of oil spill detection are shown on Figure 2(a), and 2(d). The original images are downloaded from the official website of European Satellite Agency (ESA) [15], which is European space and space-technology research organization. Their respective ground truth images shown in Figure 2(b) and 2(e) were generated based on the combination of prior knowledge and photo interpretation. These ground truth images were used to compare with simulation result images of investigated methods. These comparisons are to evaluate the accuracy of proposed method.

Figure 2. Two original images of oil spills (a) and (d), and their respective ground truth images (b) and (e). The histograms (c) and (f) are respectively ones of the original images (a) and (d). The bold rectangles in Figures (a), (b), (d) and (e) only describes the boundary of the image and are not real data.

The image in Figure 2 (a) is bi-modal one with its histogram shown in Figure 2(c), while the image in Figure 2(d) is a multi-modal one which has the histogram shown in Figure 2(f). Using these two images is to prove the proposed algorithm working well with both bi-modal and multi-modal images. The simulation results for the first stage are shown in the Figure 3. The simulation

results of four methods are images with two intensities of 0 corresponding black pixels and 255 corresponding to white pixels, in which black pixels were assumed as oil pixels. Evaluating the accuracies of the methods are performed by comparing the result images generated for the four methods with the corresponding ground truth image including adaptive mean thresholding, adaptive Gaussian thresholding methods, and Otsu method.

For instance, based on comparison of the ground truth image shown in Figure 2(b) with Figure 3(a), (b), (c) and (d), it can be qualitatively seen that, Figure 3(d) shows a better result than the remaining figures. In other words, for the qualitative view, the proposed method provided the best approximation to the ground truth image in Figure 2(b) among compared methods.

Figure 3. The simulation results of detecting oil spills in the image of Figure 2(a) by (a) the adaptive mean thresholding method, (b) the adaptive Gaussian thresholding method, (c) Otsu's method, and (d) the proposed method. The bold rectangles in images only describe the boundary of images and are not real data

For a quantitative evaluation, the proposed method was compared with the three above methods in terms of root mean square error (RMSE). More particularly, the RMSEs between each method's resultant images and the ground truth image shown in Figure 2(b) were compared together. The achieved results were listed in Table 1. It is obviously seen on Table 1 that the proposed method provides the smallest RMSE compared to the remaining methods.

Figure 4. The simulation results of detecting oil spills in the image of Figure 2(b) by (a) adaptive mean thresholding method, (b) adaptive Gaussian thresholding method, (c) Otsu's method (a), and (d) the proposed method. The bold rectangles in images are not real data.

Table 1. RMSEs for four methods using the bi-modal image shown in Figure 2(a)

Method	RMSE
AMT method	1949.31
AGT method	2126.25
Otsu method [10]	1168.89
Proposed method	548

Similarly, the simulations were performed on the second original image shown in Figure 2(d) in the second stage, which is the multi-modal image. The achieved results for the four methods were shown in Figure 4.

Qualitatively, the Figure 4(d) is the best approximation to the Figure 2(d). In other words, the proposed method provides the qualitatively best result among four compared methods. In order to evaluate the accuracy of the proposed method, the proposed method was compared with the three above methods in terms of RMSE. The comparison results were shown in Table 2. It can be seen in the Table 2 that the RMSE of the proposed method is the smallest among four investigated methods. It means that the proposed method achieves the higher accuracy than the remaining methods.

Table 2. RMSEs for four methods using the multi-modal image shown in Figure 2(d)

Method	RMSE
AMT method	1774.40
AGT method	1872.57
Otsu method [10]	2228.97
Proposed method	342.66

In the similar way, the four above investigated methods were also evaluated by using eight other SAR images with all three different histogram shapes which are uni-modal, bi-modal and multi-modal. Each image was alternately applied to these four methods to estimate their RMSE values.

As a result, there were total ten RMSE values corresponding to the ten SAR images applied to each method. Averaging these ten RMSE values provides an average RMSE value for each method. The average RMSE value was used to compare accuracy of the investigated methods.

The simulations showed that the RMSE values obtained by the proposed method are smaller than all those obtained by the remaining methods. More particularly, the average RMSE value of the proposed method calculated over the ten simulated SAR images is less than all those of the three remaining methods computed over the same ten images, as shown in Table 3.

Table 3. Average RMSE values of four methods calculated over the ten different SAR images of oil spills

Method	Average RMSE
AMT method	2014.79
AGT method	2057.11
Otsu method [10]	1480.98
Proposed method	559.92

In summary, the proposed method works well for the uni-modal, bi-modal and multi-modal images, and provides higher accuracy than other methods including the adaptive mean, thresholding, adaptive Gaussian thresholding, and Otsu methods.

4. Conclusion

The paper developed a novel algorithm for detecting oil spills on sea, which is based statistically selecting a global threshold to separate if a pixel is a dark spot in SAR images.

The results of the proposed method were compared in the qualitative and quantitative ways with the adaptive mean thresholding, and adaptive Gaussian thresholding methods and Otsu's method for both bi-modal and non-bimodal gray level images. The results of the proposed method provide higher accuracy in comparison with the three remaining methods.

In the near future, we focus on deploying this proposed algorithm in digital signal processing hardware so that it can be applied in practice for real-time applications.

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